

# Programmatic Manipulation of Type Specifiers in Common Lisp

Jim Newton

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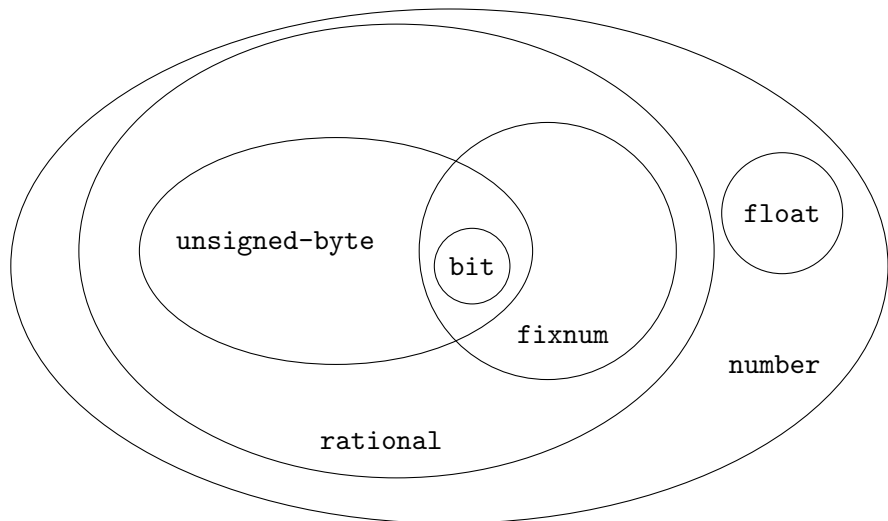
# Overview

- 1 Common Lisp Types
  - Native type specifiers
  - Type calculus with type specifiers
- 2 Reduced Ordered Binary Decision Diagrams (ROBDDs)
  - Representing CL types as ROBDDs
  - Reductions to accommodate CL subtypes
  - Type calculus using ROBDDs
  - Type checking and code generation with BDDs
- 3 Conclusion
  - Summary
  - Questions

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Types are sets. Subtypes are subsets. Intersecting types are intersecting sets. Disjoint types are disjoint sets.



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Type specifiers can be extremely **intuitive** thanks to homoiconicity.

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There are many type specifiers for the same type.



# We can ask questions with CL type specifiers.

- Type **membership**? (`typep x T1`)

$$x \in T_1$$

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- Type **equivalence**? (`and (subtypep T1 T2) (subtypep T2 T1)`)

$$(T_1 \subset T_2) \wedge (T_2 \subset T_1)$$

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- Type **equivalence**? (`(and (subtypep T1 T2) (subtypep T2 T1))`)
- Type **disjointness**? (`(subtypep '(and ,T1 ,T2) nil)`)

$$T_1 \cap T_2 \subset \emptyset$$

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- Type **disjointness**? (`(subtypep '(and ,T1 ,T2) nil)`)

Sometimes, `subtypep` returns **don't know**.

# Type expressions can be barely human readable.

```
(setf T1 '(not (or (and fixnum unsigned-byte)
                  (and number float)
                  (and fixnum float))))

(setf T2 '(or (and fixnum
                  (not rational)
                  (or (and number (not float))
                      (not number))))
            (and (not fixnum)
                  (or (and number (not float))
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```

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The **same type** may be **checked multiple times**.

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The **same type** may be **checked multiple times**. We can **do better**.



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# Type specifier viewed as a Boolean expression of variables

A CL type specifier has a dual in Boolean algebra notation.

Type specifier: `(not (or (and A C) (and B C) (and B D)))`

Boolean Expression:  $\neg ((A \wedge C) \vee (B \wedge C) \vee (B \wedge D))$

# Type specifier viewed as a Boolean expression of variables

Forget about the CL type system for the moment,  
and just concentrate on Boolean algebra with binary variables.

Boolean Expression:  $\neg ((A \wedge C) \vee (B \wedge C) \vee (B \wedge D))$

# Type specifier viewed as a Boolean expression of variables

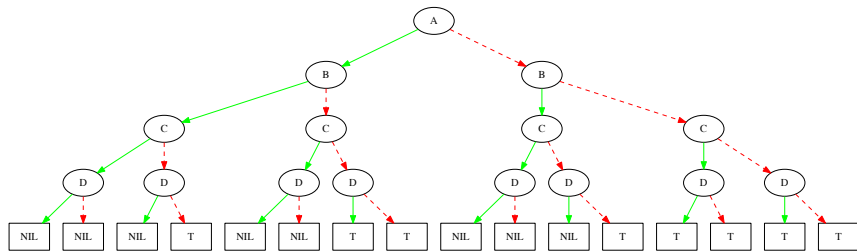
If we *order* the variables,  
then every Boolean expression has a unique truth table.

Boolean Expression:  $\neg ((A \wedge C) \vee (B \wedge C) \vee (B \wedge D))$

# Type specifier viewed as a Boolean expression of variables

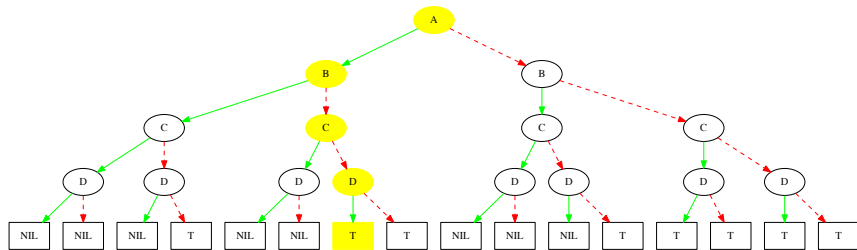
The truth table can be represented as an OBDD, **ordered** binary decision diagram. A **green arrow** a variable being true; a **red arrow** represents the variable being false.

Boolean Expression:  $\neg ((A \wedge C) \vee (B \wedge C) \vee (B \wedge D))$



# Type specifier viewed as a Boolean expression of variables

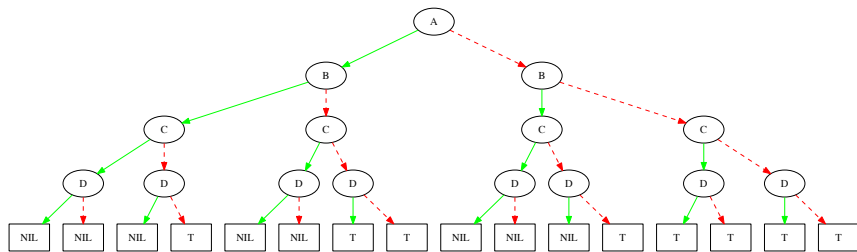
Every path from root to leaf corresponds to one row of the truth table.



A	B	C	D	$\neg((A \wedge C) \vee (B \wedge C) \vee (B \wedge D))$
T	⊥	⊥	T	T
⊥	T	T	⊥	⊥



# Type specifier viewed as a Boolean expression of variables



4 variables  $\implies 2^{4+1} - 1 = 31$  nodes

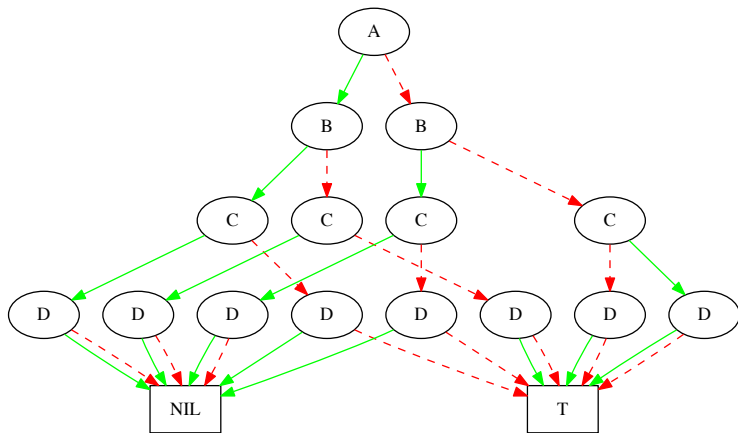
The graph size **grows exponentially** with number of variables.

We can **do better**.



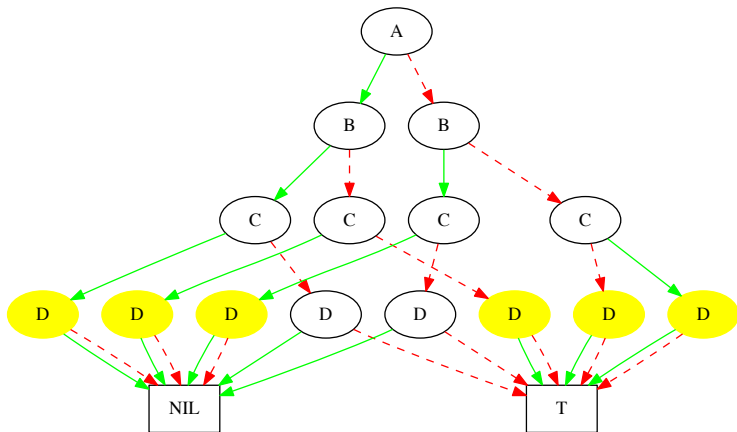
## Standard Rule 1: the *terminal* rule

There are 3 standard reduction rules. The terminal rule allows us to replace leaf nodes with **singleton objects**, NIL and T. Divides size by 2.

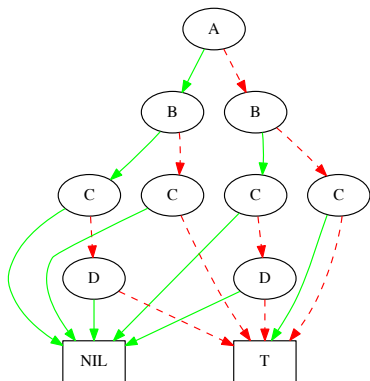


## Standard Rule 2: the *deletion* rule

The deletion rule allows us to remove nodes which have the same **red** (false) and **green** (true) pointer.

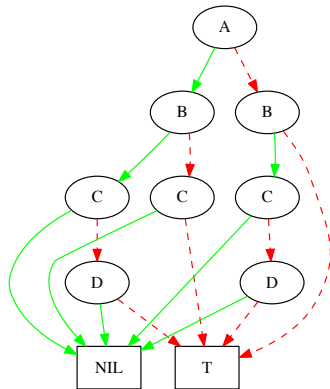
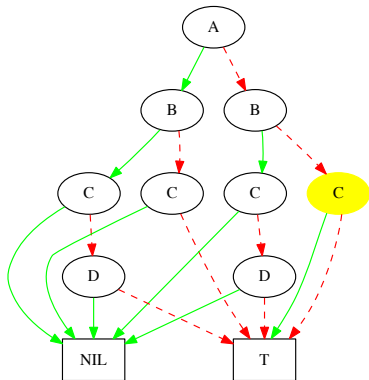


# Reducing to 11 nodes



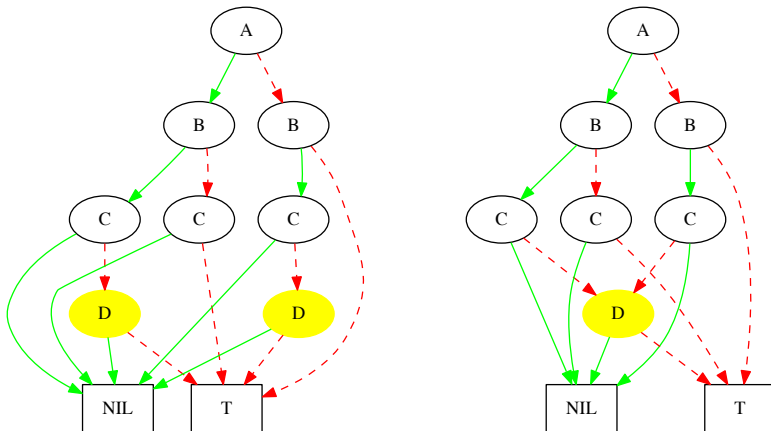
# More reduction

The deletion rule can be applied multiple times.



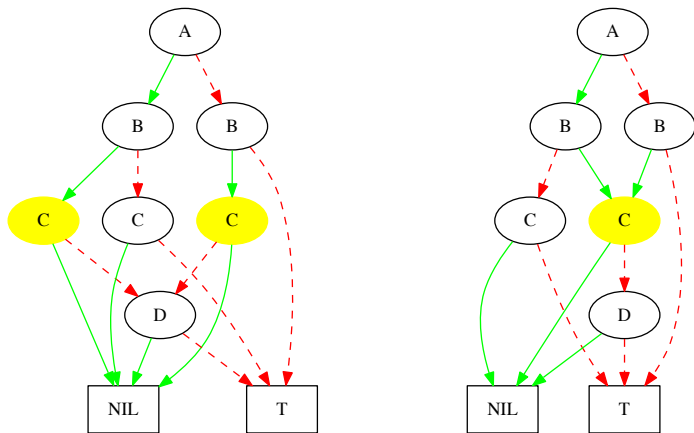
## Standard Rule 3: the *merging* rule

The merging rule allows us to merge structurally **congruent** nodes, *i.e.*, with **same children**, and **same label**.



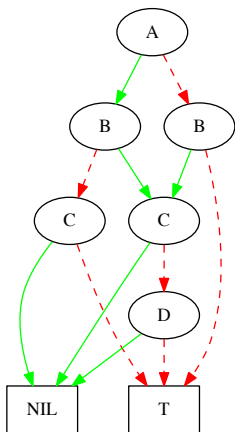
# More congruent nodes

The merging rule can be applied multiple times.



# ROBDD: Reduced ordered binary decision diagram

Started with 31 nodes, we can represent the CL type specifier with only 8 nodes.

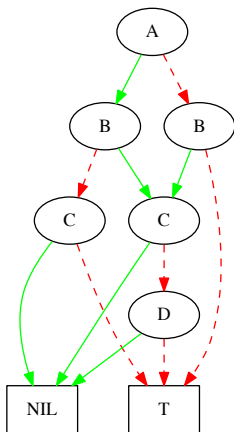


```
(not (or (and A C)
         (and B C)
         (and B D)))
```

Standard algorithm to **serialize** to a **canonical disjunctive** form.

```
(or (and A (not B) (not C))
    (and A B (not C) (not D))
    (and (not A) B (not C) (not D))
    (and (not A) (not B)))
```

## ROBDD: Reduced ordered binary decision diagram



```
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         (and B C)
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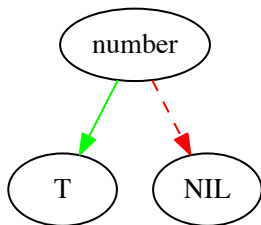
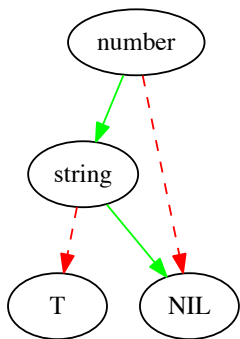
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    (and (not A) B (not C) (not D))
    (and (not A) (not B)))
```

This serialization is in **no sense minimum** in form.



# Standard ROBDD reduction rules are insufficient for CL type system.

(and number (not string)) = number are equivalent types, but the BDDs are different!



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- A solution is needed.

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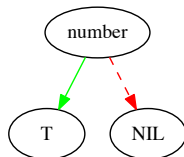
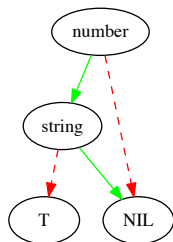
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- We find that it **does not quite work for reasoning about CL types**.
- A solution is needed.
- **We introduce a 4th reduction rule: the *subtype rule***. Our contribution.

## Subtype rule (4), CL type system compatibility

The types `number` and `string` are disjoint,  
therefore,  $\text{string} \subset \overline{\text{number}}$ .

Child to search	Relation	Reduction
$P.\text{green}$	$P \subset C$	$C \rightarrow C.\text{green}$
$P.\text{green}$	$P \subset \overline{C}$	$C \rightarrow C.\text{red}$
$P.\text{red}$	$\overline{P} \subset C$	$C \rightarrow C.\text{green}$
$P.\text{red}$	$\overline{P} \subset \overline{C}$	$C \rightarrow C.\text{red}$
$P.\text{red}$	$P \supset C$	$C \rightarrow C.\text{red}$
$P.\text{red}$	$P \supset \overline{C}$	$C \rightarrow C.\text{green}$
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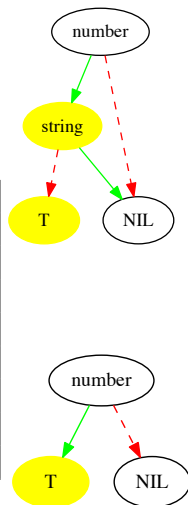




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$P.green$	$P \subset \overline{C}$	$C \rightarrow C.red$
$P.red$	$\overline{P} \subset C$	$C \rightarrow C.green$
$P.red$	$\overline{P} \subset \overline{C}$	$C \rightarrow C.red$
$P.red$	$P \supset C$	$C \rightarrow C.red$
$P.red$	$P \supset \overline{C}$	$C \rightarrow C.green$
$number.green$	$\overline{number} \supset string$	$string \rightarrow string.red$
$P.green$	$\overline{P} \supset \overline{C}$	$C \rightarrow C.green$



# Type calculus using ROBDDs

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## Questions

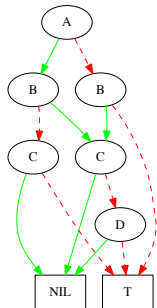
Are two types the **same**? Or **disjoint**? Or is one a **subtype** of the other?

## Functions

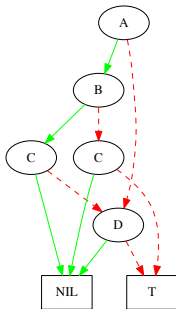
`bdd-and`, `bdd-or`, `bdd-and-not`.

Are the two types the same? No, BDDs are different.

```
(not (or (and A C)
         (and B C)
         (and B D)))
```



```
(or (and A
      (not C)
      (or (and B (not D))
          (not B)))
    (and (not A)
         (or (and B (not C) (not D))
             (not D))))
```

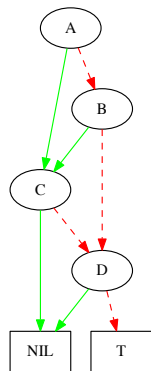


Are two types disjoint? No, the intersection is non-nil.

```
(setf T1
  (bdd '(and (not (and (not A) D))
            (not (or (and A C)
                    (and B C)
                    (and B D)))))))
```

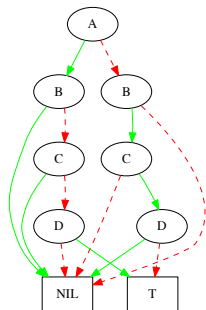
```
(setf T2
  (bdd '(or (and A
              (not C)
              (or (and B (not D))
                  (not B)))
            (and (not A)
                  (or (and B
                        (not C)
                        (not D))
                    (not D)))))))
```

(bdd-and T1 T2)



Is one a subtype of the other? Yes.  $T_1 \subset T_2$ .

(bdd-and-not T2 T1)



(bdd-and-not T1 T2)



# Run-time calls to `bdd-type-p`

```
(defun bdd-type-p (obj bdd)
  (etypecase bdd
    (bdd-false
      nil)
    (bdd-true
      t)
    (bdd-node
      (bdd-type-p obj
        (if (typep obj (bdd-label bdd))
            (bdd-left bdd)
            (bdd-right bdd)))))))
```

Guarantees that **each base-type** is **checked maximum of once**.

# Compile time call to `bdd-typep`, via `compiler-macro`

```
(bdd-typep X '(or (and sequence (not array))
                  number
                  (and (not sequence) array)))
```



# Compile time call to `bdd-typep`, via `compiler-macro`

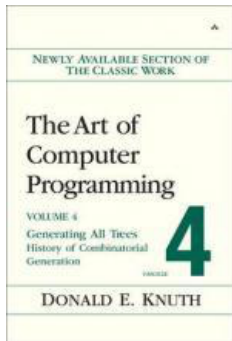
```
(bdd-typep X '(or (and sequence (not array))
                 number
                 (and (not sequence) array)))

(funcall (lambda (obj)
  (block nil
    (tagbody
      1 (if (typep obj 'array)
            (go 2)
            (go 3))
      2 (return (not (typep obj 'sequence)))
      3 (if (typep obj 'number)
            (return t)
            (go 4))
      4 (return (typep obj 'sequence))))))
X)
```

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# Donald Knuth's new toy.



Binary decision diagrams (BDDs) are wonderful, and **the more I play with them the more I love them**. For fifteen months **I've been like a child with a new toy**, being able now to solve problems that I never imagined would be tractable... **I suspect that many readers will have the same experience** ... there will always be **more to learn** about such a fertile subject. [Donald Knuth, *Art of Computer Science, Volume 4*]

# Summary

- Native CL type specifiers are
  - Powerful and intuitive
  - But may suffer performance issues
  - Missing capability (subtypep)
- ROBDDs offer an interesting alternative
  - We have extended Standard ROBDD theory to CL types
  - Shown type calculus operations, equality, intersection, relative complement, etc
  - Demonstrated efficient compile time code generation for type checking.
  - Competitive performance
- Lots more work to do.
- For more information see the LRDE website:
  - <https://www.lrde.epita.fr/wiki/User:Jnewton>

# Questions/Answers

Questions?



# ROBDD: Reduced Ordered Binary Design Diagrams

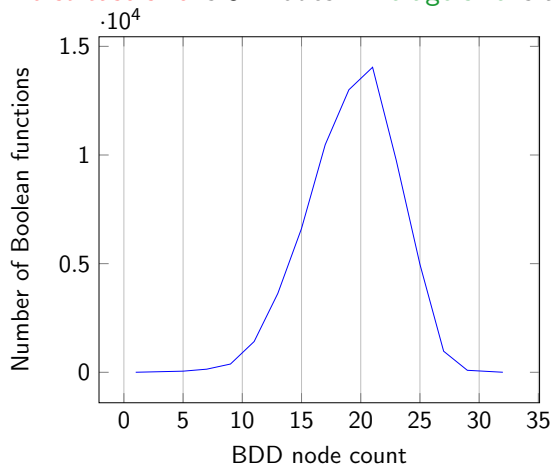
Having as **few nodes** as possible has advantages in:

- **Correctness** in presence of subtypes,
- **Memory** allocation,
- Execution **time** of graph-traversal related operations, and
- Generated **code size** (as we'll see later).

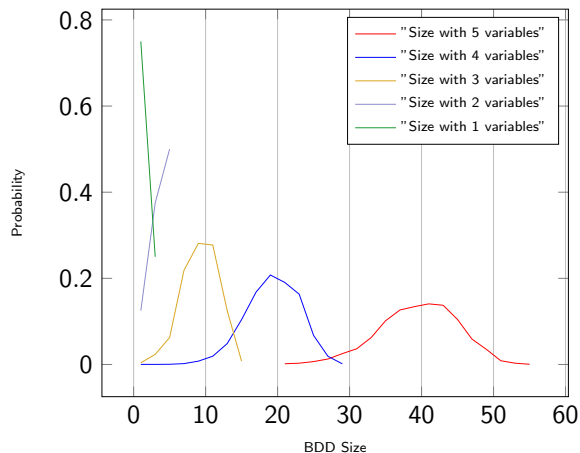
## Possible ROBDD sizes for 4 variables

Of the  $2^{2^4} = 65,536$  different Boolean functions of 4 variables, various sizes of reduced BDDs are possible.

**Worst case size** is 32 nodes. **Average size** is approximately 20 nodes.



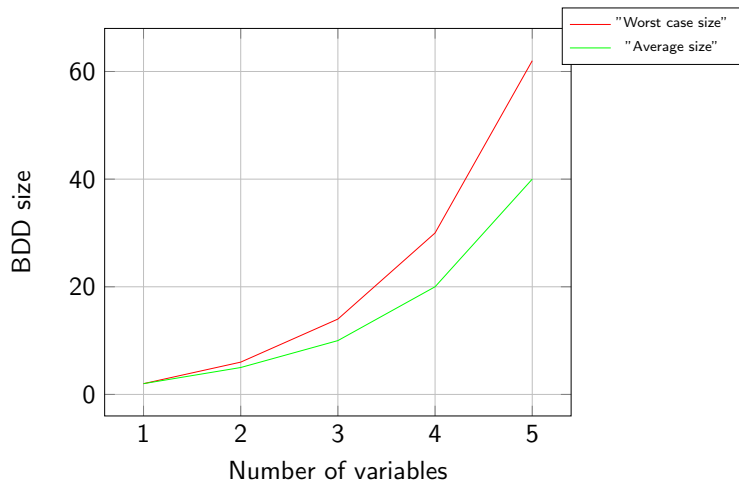
# Distributions for 2 to 5 variables



Distribution of ROBDD size over all possible Boolean functions of N variables.



# Expected and worst case ROBDD size



FIRST TRY: Expands to the following.  $O(2^n)$  code size.  
 $O(n)$  execution time.

If the type specifier is known at compile time.

```
(funcall (lambda (obj)
  (if (typep obj 'array)
      (if (typep obj 'sequence)
          nil
          t)
      (if (typep obj 'number)
          t
          (if (typep obj 'sequence)
              t
              nil))))))
X)
```

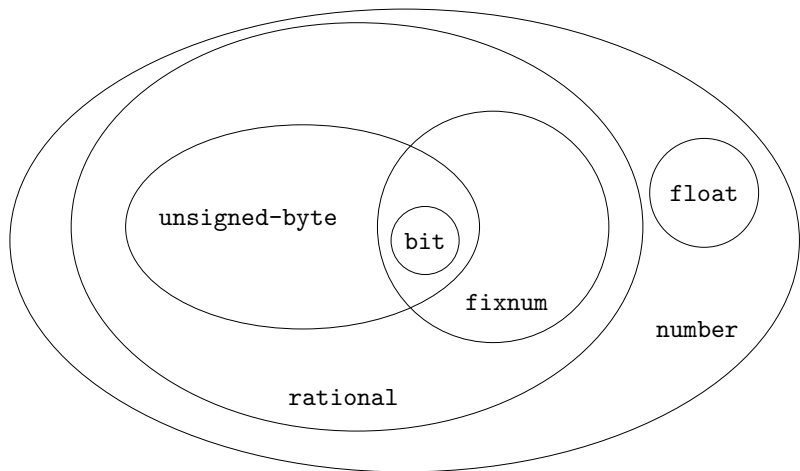
We can do better.

BETTER:  $\mathcal{O}(2^{\frac{n}{2}})$  code size.  $\mathcal{O}(n)$  execution time.<sup>1</sup>

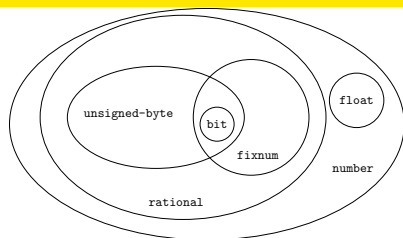
```
(funcall (lambda (obj)
  (labels ((#:f1 ()
            (typep obj 'sequence))
           (#:f2 ()
            (or (typep obj 'number)
                (#:f1)))
           (#:f3 ()
            (not (typep obj 'sequence)))
           (#:f4 ()
            (if (typep obj 'array)
                (#:f3)
                (#:f2))))
    (#:f4 )))
X)
```

<sup>1</sup> $\mathcal{O}(2^{\frac{n}{2}})$  is a non-rigorous estimate.

# Experimental problem: thoroughly partition a set of types



# Maximal Disjoint Type Decomposition

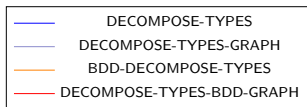
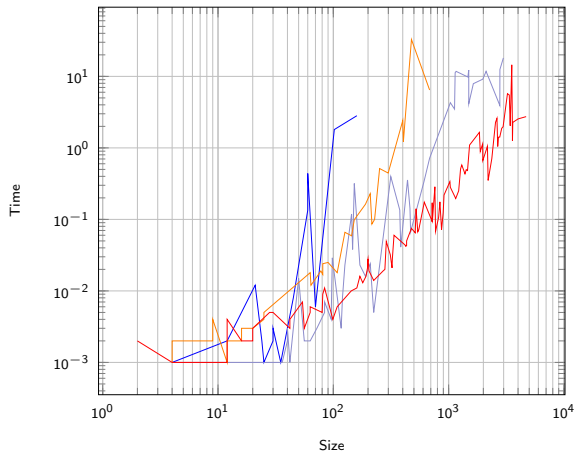


```
(bit float fixnum number rational unsigned-byte)
```

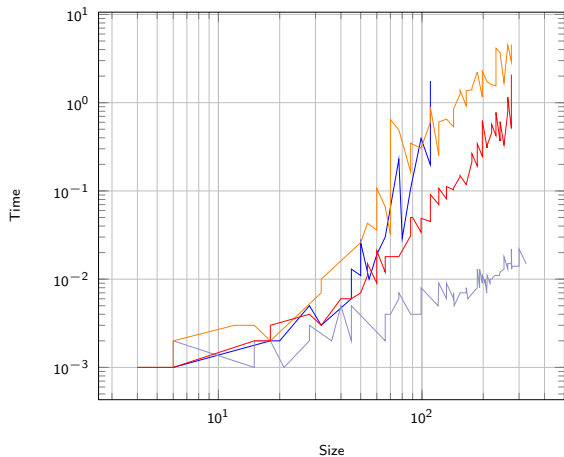
```
-->
```

```
(bit
 float
 (and fixnum unsigned-byte (not bit))
 (and fixnum (not unsigned-byte))
 (and number (not float) (not rational))
 (and rational (not fixnum) (not unsigned-byte))
 (and unsigned-byte (not fixnum)))
```

# Combinations of number and condition



# Subtypes of fixnum: (member ...)



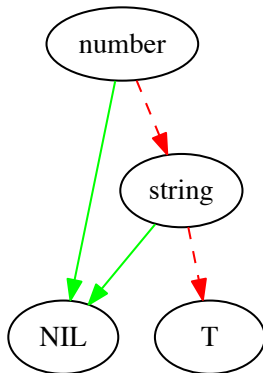
# Type specifier summary

- Easy and intuitive (thanks to homoiconicity)
- Run-time calls to `subtypep` and `typep`
- Issues of performance and correctness of `subtypep` and `typep`



# Subtypes

```
(and (not number)
      (not string))
```



# Caveat of subtypep

Sometimes `subtypep` returns *don't know*. Sometimes for good reasons. Sometimes not.

```
CL-USER> (subtypep '(satisfies oddp) '(satisfies evenp))  
> NIL, NIL
```

```
CL-USER> (subtypep 'arithmetic-error '(not cell-error))  
> NIL, NIL
```